

# HORIBA TORQUE MATCHING (HTM)

Improved Road to Rig Testing and An Alternative to Mini PEMS for Difficult Applications

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### **EPA ROVER PEMS Real Time Mass Emissions**





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## Listening to the Customer – Motorcycle Example

#### Hearing "need mini PEMS"

- Lower cost
- Reduced capabilities OK
- Reduced accuracy OK
- Low weight
- Small footprint
- Installable on an arbitrary motorcycle
- Presumably installed external to vehicle

Can we say "need best m/c data possible" instead?

- Lower cost desirable, e.g. minimum equipment purchase
- Increased capabilities desirable
- Increased accuracy/representativeness desirable
- No interference with operation of m/c
- Data can be obtained from an arbitrary m/c



# Agenda

- 1. Brief Introduction to the HORIBA Torque Matching (HTM) Method
- 2. HTM for ICE / BEV / PHEV
- 3. HTM Alternative to Mini PEMS
- 4. Summary and Potential Applications



## **Real-World Emissions (RWE) Testing Definitions**

#### Replication

Reproduction of the on-road drive on Chassis, Engine or Powertrain dynos

#### Emulation

Reproduction of an on-road drive, except for intentional differences for precision calibration, development & validation









#### Simulation

Virtual simulation of real-world driving environment connected to chassis, engine and powertrain dynos









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#### But Traditional Dyno RLC Model Is Not Robust for R2R (and nobody wants to instrument drive shafts) Driver Control of Speed

- Replicating real driving in the lab can be complicated:
- Traditional road to chassis dynamometer model (assumption):

$$F(t) = (A + B * v(t) + C * v(t)^2) + M * \frac{dv(t)}{dt}$$

• But the real world has variable road gradient:

$$F(t) = (\mathbf{A} + \mathbf{B} * \mathbf{v}(t) + \mathbf{C} * \mathbf{v}(t)^2) + \mathbf{M} * \frac{d\mathbf{v}(t)}{dt} + \mathbf{M} * \mathbf{g} * \sin(\alpha) t$$

But the real world has variable wind:

$$F(t) = (\mathbf{A} + \mathbf{B} * \mathbf{v}_g(t) + \mathbf{C} * \mathbf{v}_a(t)^2) + \mathbf{M} * \frac{d\mathbf{v}_g(t)}{dt} + \mathbf{M} * \mathbf{g} * \sin(\alpha) \mathbf{t}$$

• But the real world has variable air densities:

$$F(t)? = (A + B * v_g(t) + \frac{\rho(t)}{\rho_o} * C_0 * v_a(t)^2) + M * \frac{dv_g(t)}{dt} + M * g * \sin(\alpha) t$$

- Road load is still an idealization; road surface effects, cornering forces, imprecise road grade measurement, throttle movement differences between drivers and tests
- There must be a better way to eliminate the need for vehicle load instrumentation as well as the inaccuracy and imprecision of traditional road load control for road to rig testing ......



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1.>

Driver Control of Speed With Throttle Can Vary Widely

> A,B,C's Depend on Roads and Tires

> > Road Grade is Difficult to Measure Precisely

> > > Air Speed and Ground Speed Can Vary Widely

Aerodynamic Drag Depends on Atmospheric Conditions



### And Road Grade is Difficult to Measure and Reproduce



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## **Desirable Attributes for R2R Method Are Embodied in HTM**

HORIBA has developed a robust "Road to Rig" test method known as HORIBA Torque Matching that enables blind testing vehicles on a chassis dynamometer to replicate real-world vehicle operation performed virtually anywhere

- <u>Robustness</u> results from meticulously replicating individual controlled powertrain parameters
- <u>Blind testing</u> is ensured by requiring only parameters that are easily measured in the field no specific technical information related to the test vehicle is required
- HTM allows a <u>centralised testing location</u> to replicate tests from other road test locations for all types of road vehicles

HORIBA's Torque Matching (HTM) method has several, additional and valuable benefits:

- Road grade knowledge is not required but is implicitly accounted for because the total road load is replicated
- <u>Coastdowns and coastdown coefficients are not used</u> because the load is not based on a road load model, but on load replication whereby all road load and changing road surfaces are implicitly accounted for
- Real-world <u>wind conditions are also implicitly replicated</u>
- <u>Conventional test cell hardware</u>, with the addition of MEDAS and HORIBA software can be used
- Matching road load while emulating different ambient conditions, or after component substitutions can help diagnose vehicle failure modes



# **HORIBA Torque Matching (HTM) Method in General**

3 Steps to Precision Real-World Testing in the Laboratory Under Any Real-World Conditions

**Road Test** 



- Record speed, pedals, ambient conditions
- Any grade, surface, weather, altitude, and cornering
- Optionally measure emissions for validation (concentrations only – 5 gas analyzer)

#### Lab Replication/Validation



- MEDAS replicates ambient
- Dyno replicates speed
- Robot driver replicates pedal or throttle
- Dyno torque *recorded*
- Emissions and load match road test

#### **Optional Lab Emulation**



- MEDAS emulates ambient
- Dyno replicates speed
- Robot driver replicates *dyno torque*
- Change engine calibration or emission controls
  as desired and repeat test for comparison
- Emissions and load would match road test if run

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#### **Road-to-Chassis Goal**

#### Potential geographic diversity of testing locations for centralised laboratory testing

- Replicate a road test from anywhere in a central lab
- Emulate same test under different ambient or seasonal conditions, or evaluate failure modes
- Evaluate the effects of component substitution on emissions performance
- Evaluate the effects of alternative calibrations
- Evaluate the absolute effects of lubricant and fuel blends across well defined, fully controlled real-world driving scenarios.





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# **Replication of Pure EV is Simplest Application of HTM**



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#### **PHEV Test Setup in Lab and On-Road**

#### Test cell (HOR E-LAB cell3)



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Independent Testing in Japan by applications group, independent from HTM developers

HOR OBS-ONE GS/PN





## PHEV Real-World, On-Road Test



### **Superior Replication of PHEV Control Parameters**



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### **Reproduction of ICE Resulting Operational Parameters**





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# **Reproduction of ICE Resulting Operational Parameters**









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#### **Reproduction of EV Resulting Operational Parameters**





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# **HORIBA Torque Matching (HTM) Method - Motorcycles**

3 Steps to Precision Real-World Testing in the Laboratory Under Any Real-World Conditions

**Road Test** 



- Record speed, pedals, ambient conditions (engine speed or gear shifts)
- Any grade, surface, weather, altitude, and cornering
- Optionally measure emissions for validation (concentrations only with small 5 gas analyzer)



#### Lab Replication/Validation



- MEDAS replicates ambient
- Dyno replicates speed
- Robot driver replicates pedal or throttle
- Dyno torque *recorded*
- Emissions and load match road test (Motorcycle robot for throttle, brakes, and gear shifts)

#### **Optional Lab Emulation**



- MEDAS emulates ambient
- Dyno replicates speed
- Robot driver replicates *dyno torque*
- Change engine calibration or emission controls as desired and repeat test for comparison
- Emissions and load would match road test if run



# HTM vs. Mini-PEMS for Motorcycles (+/-): Net +

- Any pollutant or parameter that can be measured in the lab can be measured from a motorcycle while replicating or emulating a real-world drive – high precision, accuracy, and breadth of measurements
- Exhaust flow measurement does not need to be roadworthy
- Avoids effects of wind and ambient effects on gas analyzers
- Real-world emissions events of interest can be reproduced for diagnostic purposes in the lab
- Some emissions events can be eliminated using the precision of the lab once they've been diagnosed
- A single road drive can be used as the base test for multiple HTM tests conducted under different weather conditions or with different powertrain calibrations or replaced faulty components
- An alternative and suitable mini-PEMS still needs to be developed and may not get to market in a usable form factor or with desired accuracies and breadth of measurements – HTM uses existing gas analyzers and flow measurement
- Program measurement errors using Mini-PEMS will be comprised of: concentration errors (analyzer quality and environmental factors), flow errors, instrumentation aerodynamic effects, unavailability of instruments for some pollutants?
- Program measurement errors using HTM results in smaller concentration errors, smaller flow errors, HTM replication discrepencies



### HTM for Higher Quality Overall M/C Testing Program





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### **HTM Replication Extends Lab Measurements to Real-World**

- Screening road tests can be replicated in the laboratory for diagnostic purposes
- What are the real-world emissions of trace pollutants for which no portable instruments exist?
- Low NOx real-world vehicle/engine testing using laboratory measurements enabled by HTM replication
- Motorcycles can be tested without custom installations or fabrications of flow meters
- High quality data for regulation development, e.g. motorcycles
- HD/LD In-Use Test Programs, e.g. finding real-world problems (HTM Step 1), diagnosing them in the lab (HTM Step 2), then proving fixes by component substitutions or calibration changes (HTM Step 3)



## HTM Emulation (Step 3) Answers What-if's

A vehicle met the required emissions standards at sea level in warm weather, what if:

- The temperature was colder?
- It was operating at a higher altitude?

An in-use vehicle failed to meet the required emissions standards either on the road with PEMS, or during an HTM replication test, what if:

A suspect EGR valve was replaced?

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- A suspect catalytic converter was replaced?
- A suspect leaky fuel injector was replaced?

How would a baseline emissions inventory or emissions map of a geographic area or commuter corridor improve if experimental emissions controls were demonstrated on high volume vehicles, or how much would emissions geofencing degrade emissions in a geographic area – differences in traffic and weather are avoided, i.e. test results reflect only the intentional change. HORIBA





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